

# VC431

tries

terrain.

### Triaxial Vibrometer

posure to vibration.

The VC431 is a high performance vibrometer; the ideal instrument for measuring vibration according to:

Directive 2002/44/EC on risks deriving from workers' ex-

The VC431 enables the user simply and comfortably to

follow the technical guides for the evaluation and preven-

tion risks related to mechanical vibration of most coun-

The VC431 can also evaluate the effect of vibration on the

• The UNE 22-381-93 Standard Control of vibrations produced by blasting with explosives and transmitted by the

· Nacional laws and regulations on noise and vibrations:

°Vibrations transmitted to the hand-arm system (HA)

°Vibrations transmitted to the whole body (WB)

<sup>o</sup>Whole body in buildings vibrations (WBB)

structure of buildings and the terrain:

Applications

- Assessment of workers' exposure to vibration:
  - Hand Arm (HA) 2002/44/EC ISO 5349-1 ISO 5349-2
  - Whole Body (WB) 2002/44/EC ISO 2631-1
- Assessment of vibration in buildings:
  - ISO 2631-2 (Buildings)
- Evaluation of the effect of vibration on the Structure of buildings and the terrain:
  - UNE 22-381-93

### User-Friendly

- Measures all parameters simultaneously for each application (HA, WB, Buildings and Structure).
- Single measurement scale, independent of the application (HA, WB, Buildings, and Structure).
- Projected information displayed during the measurement.
- Large 3,2" high resolution, backlit graphic display.
- Just three operating keys (Soft key).

### **Characteristics**

- Large storage capacity; saves the time history of the measurement.
- Downloading and powering via USB port.
- Projection of parameters; evaluation of exposure to vibration for measurement times below the exposure time.
- Software: CESVA Capture Studio (SFT030) and CESVA Studio Editor (optional).
- Accelerometer different for each application (HA, WB, Buildings/Structure).
  - LION (NA, WB, Bundings/Structure).
  - Vibrometer complies with norm ISO 8041.

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Triaxial Vibrometer

VC431

Following the philosophy that characterises all **CESVA** instruments, the **VC431** is user-friendly, with a single range (no scale changes) and simultaneous measurement of all parameters.

It has an intuitive, visual menu and option structure. There is no need to set the language as it has easily recognisable and identifiable icons.

Any application or adjustment can be accessed from the main menu. To do this simply select the icon required.

It has three vibration measurement applications: Hand Arm (HA), Whole Body (WB), Whole Body in Buildings (WBB) and Structure (S). These comply with European directive 2002/44/CE on risks at work from vibration, and with ISO 2631-2.

The vibrometer enables the user to work with triaxial accelerometers as each of its measurement applications requires a specific triaxial accelerometer.

For the sake of comfort, the sensitivity adjustments of various accelerometers are saved so that there is no need to carry out a sensitivity adjustment every time a measurement is carried out in a different mode.

The VC431 enables all the necessary parameters to be measured simultaneously, to evaluate exposure to vibration in  $m/s^2$  or dB (dB only available for buildings), with the appropriate weightings: Wd [x,y] and Wk [z] for WB, Wh [x,y,z] for HA and Wm [x,y,z] for WBB. It also has a large memory for storing both final results and the time history of the parameters measured, so they can subsequently be recalculated for any stretch.

The registers saved in the memory can be deleted via menu of the VC431. All the registers can be deleted at once, or just a selected one.

In addition it enables measurements shorter than the exposure time to be made, as it displays onscreen the parameters projected to the expected exposure time (programmable projection time  $[t_p]$ ). The CESVA Capture Studio (SFT030) computer software is included with the vibrometer. This application enables measurements carried out with the instrument to be downloaded via the USB port, and the results analysed quickly and simply. While it is connected to the USB port of a computer it does not need batteries as it is powered via the computer's USB.

The VC431 does not only make the task of measuring and evaluating vibration easier, it also provides all the necessary data for worker information and training on the significance and potential risks of the results of the measurements carried out.

Its reduced weight, versatility and user-friendliness make it the hand-held instrument *par excellence* for evaluations of risks related to vibration. The VC431 is a personal instrument; the workers themselves can carry it to evaluate their exposure to vibration.



CESVA VC431 acoustic instruments

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z h 1.0	0.09787		
	ahy	A(8)	A(8)p
	0.27428	0.10236	0.97873
Ē	87	5/256	
[ tp			

Modo Hand Arm (HA)

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0 tp himm A(8) A(8)p				
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ED 28% 50/256				
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### **Modo Whole Body**

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i	ω	k	awi	MTVVi	
X	M	1.0	91.94	104.70	
Ų	m	1.0	92.07	104.64	
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			а <sub>МV</sub>	MTVV	MTVVy
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E 28% 50/256					
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### Modo Whole Body edificación (WBB)



Modo Estructura (S)

## Functions available

Func. Description of HAND ARM (HA) Mode functions

a <sub>hx</sub>	Rms value of acceleration in the x axis with $W_h$ weighting
a <sub>hy</sub>	Rms value of acceleration in the y axis with $W_h$ weighting
a <sub>hz</sub>	Rms value of acceleration in the z axis with $W_h$ weighting
a <sub>hv</sub>	Total value of acceleration
A(8)	Daily exposure to vibration
A(8) <sub>p</sub>	Projected daily exposure to vibration
t <sub>p</sub>	Projection time (programmable)
t	Measurement time
Euro	Description of WHOLE RODY (WR) Mode functions
runc.	Prevalue of appelaration in the x exis with W, weighting
a <sub>dx</sub>	
a <sub>dy</sub>	Rms value of acceleration in the y axis with $W_d$ weighting
a <sub>kz</sub>	Rms value of acceleration in the z axis with $W_k$ weighting
A <sub>x</sub> (8)	Daily exposure to vibration in the x axis
A <sub>y</sub> (8)	Daily exposure to vibration in the y axis
A <sub>z</sub> (8)	Daily exposure to vibration in the z axis
A <sub>x</sub> (8) <sub>p</sub>	Projected daily exposure to vibration in the x axis
A <sub>y</sub> (8) <sub>p</sub>	Projected daily exposure to vibration in the y axis
$A_z(8)_p$	Projected daily exposure to vibration in the z axis
A(8)	Daily exposure to vibration
A(8) <sub>p</sub>	Projected daily exposure to vibration
t <sub>p</sub>	Projection time (programmable)
t	Measurement time
·	
Func.	Description of WHOLE BODY in buildings Mode functions
Func. a <sub>mx</sub>	Description of WHOLE BODY in buildings Mode functions Rms value of acceleration in the x axis with $W_m$ weighting
Func. a <sub>mx</sub> a <sub>my</sub>	Description of WHOLE BODY in buildings Mode functions Rms value of acceleration in the x axis with W <sub>m</sub> weighting Rms value of acceleration in the y axis with W <sub>m</sub> weighting
Func. a <sub>mx</sub> a <sub>my</sub> a <sub>mz</sub>	Description of WHOLE BODY in buildings Mode functions   Rms value of acceleration in the x axis with Wm weighting   Rms value of acceleration in the y axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting
Func. a <sub>mx</sub> a <sub>my</sub> a <sub>mz</sub> a <sub>mv</sub>	Description of WHOLE BODY in buildings Mode functions   Rms value of acceleration in the x axis with Wm weighting   Rms value of acceleration in the y axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Total combined acceleration value
Func. a <sub>mx</sub> a <sub>my</sub> a <sub>mz</sub> a <sub>mv</sub> MTVV <sub>x</sub>	Description of WHOLE BODY in buildings Mode functions   Rms value of acceleration in the x axis with Wm weighting   Rms value of acceleration in the y axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Slow max acceleration value in the x axis with Wm weighting
Func. a <sub>mx</sub> a <sub>my</sub> a <sub>mz</sub> a <sub>mv</sub> MTVV <sub>x</sub>	Description of WHOLE BODY in buildings Mode functions   Rms value of acceleration in the x axis with Wm weighting   Rms value of acceleration in the y axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Total combined acceleration value   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the y axis with Wm weighting
Func. a <sub>mx</sub> a <sub>my</sub> a <sub>mz</sub> a <sub>mv</sub> MTVV <sub>x</sub> MTVV <sub>y</sub>	Description of WHOLE BODY in buildings Mode functions   Rms value of acceleration in the x axis with Wm weighting   Rms value of acceleration in the y axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Total combined acceleration value   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the y axis with Wm weighting   Slow max acceleration value in the y axis with Wm weighting   Slow max acceleration value in the z axis with Wmm weighting
Func. a <sub>mx</sub> a <sub>my</sub> a <sub>mz</sub> a <sub>mv</sub> MTVV <sub>x</sub> MTVV <sub>y</sub> MTVV <sub>z</sub>	Description of WHOLE BODY in buildings Mode functions   Rms value of acceleration in the x axis with Wm weighting   Rms value of acceleration in the y axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Total combined acceleration value   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the y axis with Wm weighting   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the x axis with Wm weighting
Func. a <sub>mx</sub> a <sub>my</sub> a <sub>mz</sub> a <sub>mv</sub> MTVV <sub>x</sub> MTVV <sub>y</sub> MTVV <sub>z</sub> MTVV t	Description of WHOLE BODY in buildings Mode functions   Rms value of acceleration in the x axis with Wm weighting   Rms value of acceleration in the y axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Total combined acceleration value   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the y axis with Wm weighting   Slow max acceleration value in the x axis with Wmm weighting   Slow max acceleration value in the z axis with Wmmm weighting   Slow max acceleration value in the z axis with Wmmmmm   Slow max acceleration value in the z axis with Wmmmm   Measurement time
Func. a <sub>mx</sub> a <sub>my</sub> a <sub>mz</sub> a <sub>mv</sub> MTVV <sub>x</sub> MTVV <sub>y</sub> MTVV <sub>z</sub> MTVV t	Description of WHOLE BODY in buildings Mode functions   Rms value of acceleration in the x axis with Wm weighting   Rms value of acceleration in the y axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Total combined acceleration value   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the y axis with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value with Wmm weighting   Slow max acceleration value in the z axis with Wmm weighting   Slow max acceleration value in the z axis with Wmmmm   Measurement time
Func. a <sub>mx</sub> a <sub>my</sub> a <sub>mz</sub> a <sub>mv</sub> MTVV <sub>x</sub> MTVV <sub>y</sub> MTVV <sub>z</sub> MTVV t	Description of WHOLE BODY in buildings Mode functions   Rms value of acceleration in the x axis with Wm weighting   Rms value of acceleration in the y axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Total combined acceleration value   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the y axis with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value in the z axis with Wmm weighting   Slow max acceleration value in the z axis with Wmm weighting   Slow max acceleration value with Wmmm weighting   Slow max acceleration value of the z axis with Wmmmmm   Peak value of the speed vector on the x axis
Func. a <sub>mx</sub> a <sub>my</sub> a <sub>mz</sub> a <sub>mv</sub> MTVV <sub>x</sub> MTVV <sub>y</sub> MTVV <sub>z</sub> MTVV t Func. V <sub>pkx</sub>	Description of WHOLE BODY in buildings Mode functions   Rms value of acceleration in the x axis with Wm weighting   Rms value of acceleration in the y axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Total combined acceleration value   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the y axis with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value in the z axis with Wmm weighting   Slow max acceleration value in the z axis with Wmm weighting   Slow max acceleration value in the z axis with Wmmmm   Slow max acceleration value with Wmmmm   Plow max acceleration value with Wmmmmm   Plow max acceleration value with Wmmmm   Plow max acceleration value with Wmmmmm
Func.     a <sub>mx</sub> a <sub>my</sub> a <sub>mz</sub> a <sub>mv</sub> MTVV <sub>x</sub> MTVV <sub>y</sub> MTVV <sub>z</sub> MTVV     MTVV     Vpkx     Vpky	Description of WHOLE BODY in buildings Mode functions   Rms value of acceleration in the x axis with Wm weighting   Rms value of acceleration in the y axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Total combined acceleration value   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the y axis with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value in the z axis with Wmm weighting   Slow max acceleration value in the z axis with Wmm weighting   Slow max acceleration value with Wmmm weighting   Slow max acceleration value with Wmmmmmmm   Peak value of the speed vector on the x axis   Peak value of the speed vector on the y axis   Peak value of the speed vector on the y axis
Func.     a <sub>mx</sub> a <sub>my</sub> a <sub>mz</sub> a <sub>mv</sub> mv     MTVV <sub>x</sub> MTVV <sub>y</sub> MTVV <sub>z</sub> MTVV     MTVV     Vpkx     v <sub>pky</sub> v <sub>pkz</sub> f <sub>v</sub>	Description of WHOLE BODY in buildings Mode functions   Rms value of acceleration in the x axis with Wm weighting   Rms value of acceleration in the y axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Total combined acceleration value   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the y axis with Wm weighting   Slow max acceleration value in the y axis with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value with Wm weighting   Peak value of the speed vector on the z axis   Peak value of the speed vector on the x axis   Peak value of the speed vector on the z axis   Peak value of the speed vector on the z axis   Peak value of the speed vector on the z axis   Peak value of the speed vector on the z axis
Func.     a <sub>mx</sub> a <sub>my</sub> a <sub>mz</sub> a <sub>mv</sub> MTVV <sub>x</sub> MTVV <sub>y</sub> MTVV <sub>z</sub> MTVV     MTVV     y <sub>pkx</sub> v <sub>pkx</sub> v <sub>pkz</sub> f <sub>x</sub> f <sub>y</sub>	Description of WHOLE BODY in buildings Mode functions   Rms value of acceleration in the x axis with Wm weighting   Rms value of acceleration in the y axis with Wm weighting   Rms value of acceleration in the z axis with Wm weighting   Total combined acceleration value   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the x axis with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value in the z axis with Wm weighting   Slow max acceleration value with Wm weighting   Measurement time   Description of STRUCTURE (S) Mode functions   Peak value of the speed vector on the x axis   Peak value of the speed vector on the y axis   Peak value of the speed vector on the z axis   Frequency at which the vpkx value takes place   Frequency at which the vpkx value takes place

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t

Measurement time





AC031 accelerometer for Hand-arm





AC032 accelerometer for Buildings/ Structure



AC033 accelerometer for Whole body

### **Accelerometers**

The VC431 vibrometer operates with the following triaxial accelerometers :

- AC031 Triaxial accelerometer for the Hand-arm application
- AC032 Triaxial accelerometer for the Buildings/Structure application
- AC033 Triaxial accelerometer for the Whole body application

### **Technical Specifications**

### AC031 (includes cable and accessories)

IEPE triaxial piezoelectric accelerometer (shear design) Sensitivity: 10 mV/g Margin of frequencies (10%): 0.4 Hz at 17000 Hz Operating margin: -20 at 120 °C Weight: 14 g (without cable) Assembly: M3 Thread

### AC032 (includes cable)

IEPE triaxial piezoelectric accelerometer (shear design) Sensitivity: 500 mV/g Margin of frequencies (10%): 0.13 Hz at 4800 Hz Operating margin: -30 a 90 °C Weight: 365 g (without cable) Assembly: M8 Thread

### AC033 (includes cable)

IEPE triaxial piezoelectric accelerometer (bending design) Sensitivity: 100 mV/g Margin of frequencies (10%): 0.25 Hz at 4000 Hz Operating margin: -10 at 50 °C Weight: 310 g (without cable) Assembly: On seat or with strap





CV211\* Vibration Calibrator



Handle (AA031) and tool (AA131) adapters for the AC031accelerometer

\*Accessories not included with the VC431.

### Accessories included with the VC431

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FN431	Case
STF030	Computer program
CN1US	USB cable miniature connector—USB
	I wo 1,5 volt batteries

### **Optional accessories**

CV211	Vibration calibrator for accelerometers
AA144	Mounting adapter to check the AC033 accelerometer
TR-40	Tripod (height 1,10 m)
TR050	Tripod (height 1,55 m)
ML12	Carrying case (39x32x12 cm)
AM301	Mains power feeder with USB

- CP015 1,5V 2600mA battery charger
- PB015 1,5V 2600mA rechargeable battery

### Accessories included with the AC031 accelerometer

- **AA031** Handle adapter for the AC031 accelerometer
- AA131 Tool adapter for the AC031 accelerometer

#### Accessories included with the AC032 accelerometer

CN032 Connection cable from the AC032 accelerometer to the VC431 vibrometer

### Accessories included with the AC033 accelerometer

AA033 Strap adapter for the AC033 accelerometer



VC431

### Technical specifications

### **Certificates and regulations**

Complies with the following regulations:

- ISO 8041:2005 and ISO 8041:2005/Cor1:2007
- UNE-EN ISO 8041:2006 and UNE-EN ISO 8041:2006 /AC:2009
- CE Mark. Complied with the directive on low voltage 73/23/EEC and directive CEM 89/336/EEC modified by 93/68/EEC
- The VC431 complies with directives 2002/96/EC and 2003/108/EC on WEEE (Waste Electrical and Electronic Equipment)

### **Range of linearity**

Hand Arm Application

At reference frequency of (80 Hz): acceleration in m/s<sup>2</sup>

	Band-limiting	Wh
Upper limit	3800	767.6
Lower limit	0.038	0.038

#### Whole Body Application

At reference frequency of (80 Hz): acceleration in  $m/s^2$ 

	Band-limiting	Wh	Wk
Upper limit	380	47.918	293.284
Lower limit	0.0038	0.0038	0.0038

### Whole Body in Buildings Application

At reference frequency of (16 kHz): acceleration in m/s<sup>2</sup>

	Band-limiting	Wm
Upper limit	76	25.55
Lower limit	0.00076	0.00076

#### Structure Application

At reference frequency of (16 kHz): velocity in m/s<sup>2</sup>

Band-limiting

Upper limit 1.07480

Lower limit 0.000010748 Maximum error in frequency measurement: 2%

### Total noise inherent in environmental conditions

• Hand Arm Application, with A	C031	
	Wh	
l otal noise	0.00365	
Whole Body Application, with	AC033	
	Wd	Wk
Total noise	0.00191	0.00181
Whole Body in Buildings App	lication, with AC032	
	Wm	
Total noise	0.00012	
Frequency weighting		

Hand Arm (HA): Wh Whole Body (WB): Wd, Wk Whole Body in buildings (WBB): Wm



VC431

### Technical specifications

### **Accelerometers (not included)**

- Hand-arm accelerometer (HA) AC031
- Whole body accelerometer (WB) AC033
- Whole body for buildings (WBB) and structure (S) accelerometer AC032

### **Parameters**

See table | Resolution: >1 %

Influence of humidity

Operating margin (in absence of condensation): 25 a 90 % Influence of temperature

-10 a +50	°C
0,5	dB
-20 a +60	°C
	-10 a +50 0,5 -20 a +60

### **Electromagnetic compatibility**

The equipment complies with the basic specifications of norm 8041 for the required immunity to a.c. power and radio frequency fields .

The equipment shows no degradation nor operational loss after exposure to electrostatic discharges.

### Capacity

Has 4 Mbytes memory.

Can store 256 registers in the memory.

Capacity (continual measurement)

Hand-arm:	43:00	hours
Whole Body:	43:00	hours
Whole body in buildings:	19:30	hours

### Power

### Two 1,5 V batteries, type LR6 size AA.

Typical duration with continuous operation

	Hand-arm:	09:30	hours	
	Whole Body:	11:30	hours	
	Whole body in buildings:	10:30	hours	
-	vinical duration with the screen light on may be less			

Typical duration with the screen light on may be less

External powering by USB port

Maximum acceptable power :  $5 V \pm 0.5$  (0.5 A)

**Dimensions and weight** 

Dimensions: 215 x 82 x 20 mm Weight: with battery 450 g; without battery 400 g



82 mm





acoustic instruments Cesva Capture Studio & Capture Studio Editor



### Cesva Capture Studio (SFT030)

The following operations can be carried out with the CESVA Capture Studio software supplied with the VC431:

- Download the registers stored in the memory of the VC431.
- Display the registers of the measurement.
- Recalculate all the parameters referring to a different exposure time t<sub>p.</sub>
- Export data and graphs to create the personalised acoustic report (totally compatible with the Windows<sup>®</sup> environment).



### Capture Studio Editor\* (CSE)

Capture Studio Editor is the software that enables data acquired by the VC431 to be edited:

- Delete intervals of the measurement that correspond to mis-• takes caused by erroneous contributions
- Selection of the most significant periods and recalculation of parameters for the period selected.
- Identification of cycles.
- Selectively export data to \*.txt, \*.xls, \*.mdb formats.

Both programs operate in the Windows 9x/Me/2000/NT/XP/ VISTA/7 environment.

\*Optional

The characteristics, technical specifications and accessories may vary without notice