

**NEW RIEGL**

**VMY<sup>®</sup>-2**



The **RIEGL VMY-2** is a compact, economically priced Dual Scanner Mapping System, that is well suited for a variety of mobile mapping applications.

The measuring head is equipped with two **RIEGL miniVUX-Series** LiDAR sensors and mounted in the well proven angled orientation as known from the **RIEGL VMX** Mobile Mapping Systems.

The system enables data acquisition with up to 200 scan lines / second and up to 400 kHz Pulse Repetition Rate.

To further increase efficiency of the mobile mapping system, the optional integration of up to four cameras allows simultaneous acquisition of imagery to complement the captured LiDAR data.



# Compact Dual Scanner Mobile Mapping System

## Typical Applications

- GIS Mapping & Asset Management
- Transportation Infrastructure Mapping
- HD Mapping for Autonomous Vehicles
- City Modeling
- Rapid Capture of Construction Sites and Bulk Material
- Open-Pit Mine Surveying
- As-Built Surveying



[www.riegl.com](http://www.riegl.com)



**Key Features**

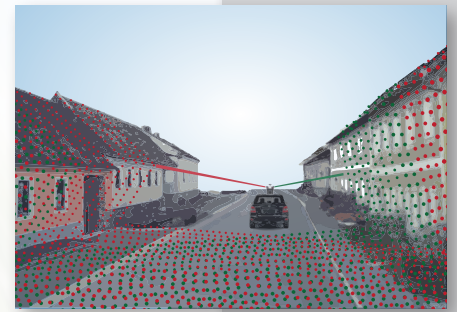
• **Compact RIEGL Dual Scanner Mobile Mapping System**

Core components of the RIEGL VMY-2 are two kinematic RIEGL miniVUX-Series LiDAR sensors, mounted in a well-proven angled orientation which enables simultaneous forward and backward looking to reduce scan shadows.

The LiDAR sensor stands out with a pulse repetition rate of up to 200 kHz at a 360 degree "full circle" field of view as well as a range accuracy of 15 mm.

Fully integrated into the measuring head of the VMY-2, the sensors enable acquisition of dense point cloud patterns even with single passes at common traffic speeds. At 80 km/h acquisition speed the typical average point density at 5 meters range operating with 400 kHz is approx. 560 points per m<sup>2</sup>.

The innovative design of the system enables folding and thus a convenient transport and space-saving storage.



360° vertical field of view @ up to 400 kHz PRR



convenient transportation

**ready for acquisition**



• **System Operation**

The VMY-2 is powered via the VM Power Supply Box. It provides power for the VMY-2MH Measuring Head, the DMI, and either for the VM-IU Interface Unit, or a data acquisition laptop. The VM Power Supply Box enables failsafe operation via a redundant power input from the vehicle's on-board power supply and a backup battery.

The VM-IU is a compact data acquisition unit for convenient system operation. It provides extended disk space to store scan data as well as camera data from the RIEGL cameras and the FLIR Ladybug®5+.

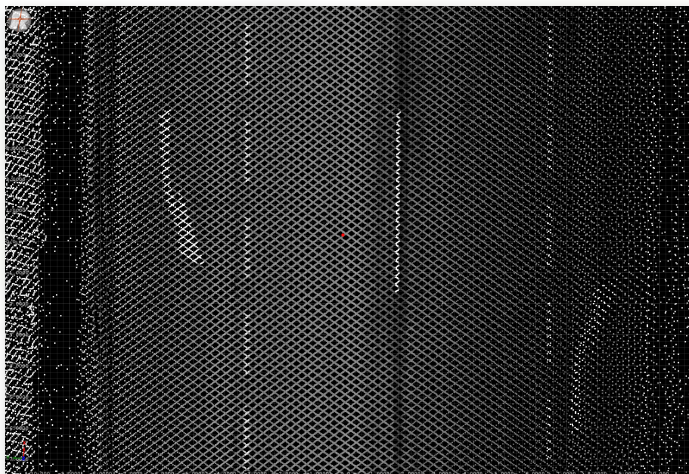
In case there is no need for RIEGL cameras, the system can also be operated with a laptop instead of the VM-IU.

• **Seamless RIEGL Workflow**

An easy-to-use interface, that is accessible via laptop or touch-screen monitor, and the RIEGL data acquisition software facilitate the operator's task in the field by providing real-time visualization of acquired scan data and imagery. The RIEGL software packages also offer comprehensive features in data processing. This covers enhanced scan data adjustment to merge overlapping mobile scan data. Furthermore it enables the scan data to be fitted to specific control objects which results in a consistent point cloud of enhanced precision and increased geo-referenced accuracy. Finally, the precise geo-referenced scan data and high resolution (panorama) images can be exported to well-known file formats, or interfaced directly with third-party software.

**VMY-2 Scan Data Examples**

**scan data cross-country (acquired at 90 km/h platform speed)**



top view, reflectance scaled



perspective view, reflectance scaled

**scan data urban environment (acquired at 30 km/h platform speed)**



perspective view showing details of the infrastructure, reflectance scaled



perspective view, reflectance scaled

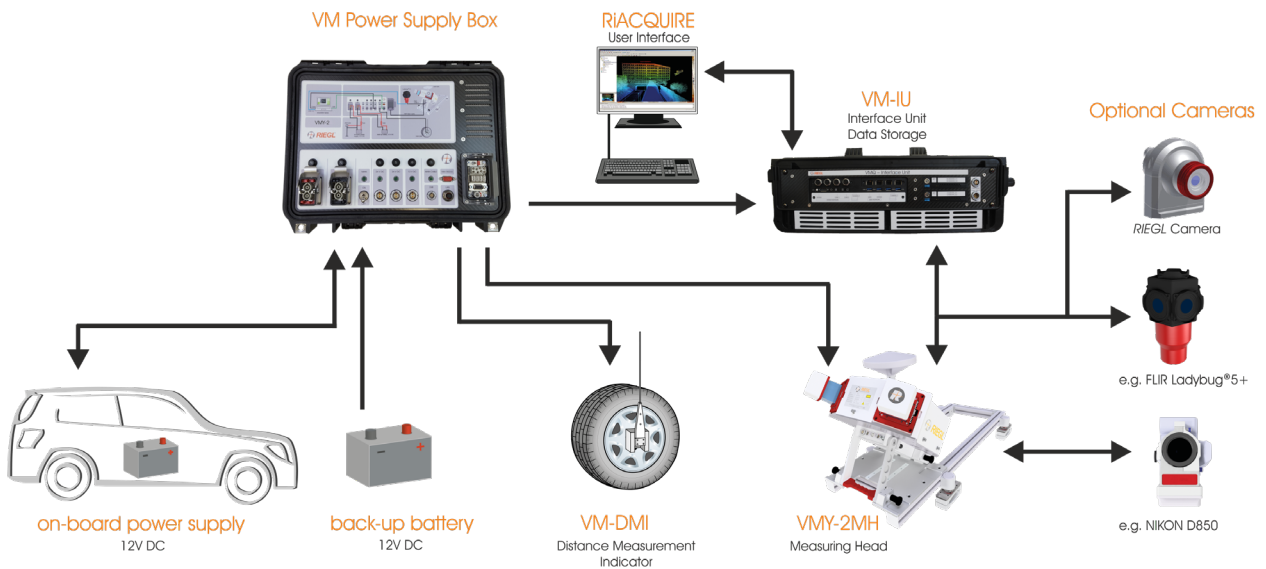
## RIEGL VMY-2 System Block Diagram

### RIEGL VMY-2 System Components

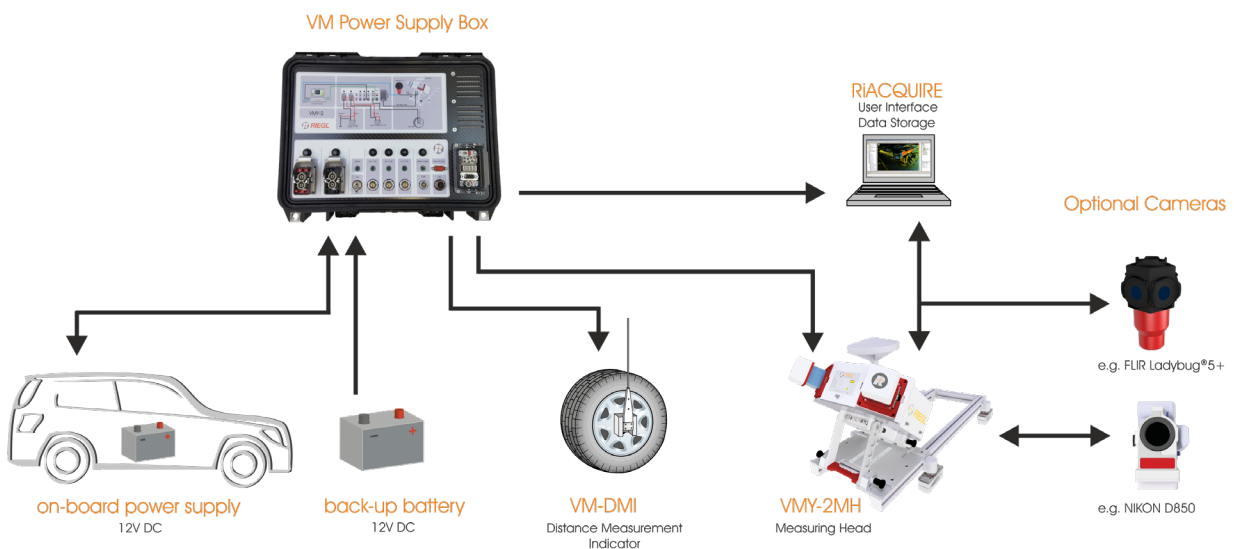
- RIEGL VMY-2MH Measuring Head
- RIEGL VM-IU Interface Unit
- RIEGL VM Power Supply Box
- VM-DMI Distance Measurement Indicator
- sustainable power supply with back-up battery
- connecting cables



RIEGL VMY-2 with VM-IU and RIEGL industrial cameras



RIEGL VMY-2 with data acquisition laptop and FLIR Ladybug<sup>®</sup>5+



**RIEGL VMY-2 Setup and Components**

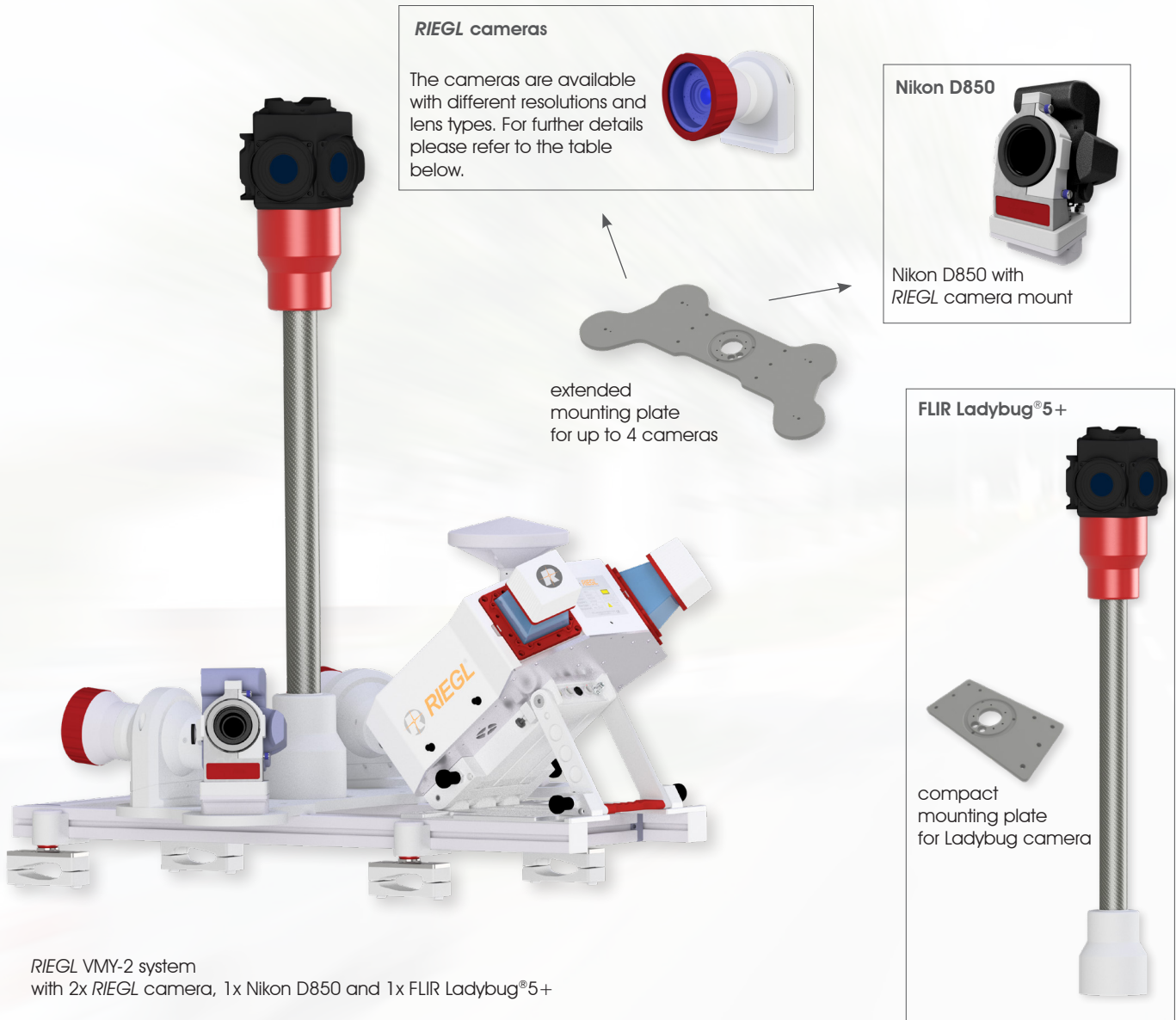


**Physical Data**

	Main Dimensions (L x W x H)	Weight (approx.)
<b>VMY-2MH Measuring Head</b> (Measuring Position) with IMU (Option A) / IMU (Option B)	405 x 436 x 437 mm	11 kg / 13 kg
<b>VMY-RM Roof Mount</b> including mounting plate and mounting brackets, without GAMS	1006 x 441 x 171 mm	12 kg
<b>VM Power Supply Box</b>	415 x 330 x 175 mm	7.8 kg
<b>VM-IU Interface Unit</b>	550 x 353 x 230 mm	14.8 kg
<b>VMY-MC Main Cable</b>	standard length 5 m	0.6 kg

## RIEGL VMY-2 Camera Options

Cameras such as 5-megapixel and 12-megapixel RIEGL cameras, high resolution DSLR cameras up to 45-megapixel, or the FLIR Ladybug®5+ spherical imaging system can be seamlessly integrated into the entire acquisition and processing workflow.




RIEGL VMY-2 system with 2x RIEGL camera, 1x Nikon D850 and 1x FLIR Ladybug®5+


Camera Options <sup>1)</sup>	max. numbers of cameras	max. frames <sup>2)</sup> per second	resolution [px (H) x px (V)]	pixel size [µm]	lens focal length [mm]	Field of View (FOV)
<b>5 MP CMOS <sup>3) 4)</sup></b>	2	20	2464 x 2056	3.45	5	80.7° x 70.7°
<b>12 MP CMOS <sup>3) 4)</sup></b>	2	8	4112 x 3008	3.45	8 / 16	83.1° x 65.9° / 47.8° x 35.9°
<b>FLIR Ladybug®5+ <sup>5)</sup></b>	1 unit / 6 lens	19	6 x [2048x2448]	3.45	4.4	90% of full sphere
<b>Nikon® D850 <sup>5)</sup></b>	4	1	8256 x 5504	4.34	14 / 20	104° x 81° / 83° x 61°


1) The combination of different cameras is possible. A maximum of 4 cameras can be integrated with the system.  
 2) Maximum frame rate of a single camera operated in 8-bit mode. The use of multiple cameras may reduce maximum frame rates.  
 3) A user defined "Region of Interest" can be defined during data acquisition, resulting in a reduction of the FOV and the resolution. This may help to reduce image file sizes on the one hand and to further increase frame rates on the other hand.  
 4) The RIEGL cameras require the usage of the VM-IU Interface Unit.  
 5) This camera can also be used with a data acquisition laptop instead of the VM-IU Interface Unit.



## RIEGL VMY-2 Technical Data


 max. measurement range

 pulse repetition rate (peak)

 online waveform processing

 optional digital camera

 multiple target capability

 eye safe operation at Laser Class 1

### VMY-2 Scanner Performance

<b>Laser Class</b>	Laser Class 1 (Class 1 Laser Product according to IEC 60825-1:2014)
<b>Effective Measurement Rate <sup>1)</sup></b>	400 kHz
<b>Max. Range, Target Reflectivity <math>\rho \geq 80\%</math> <sup>2)</sup></b>	280 m
<b>Max. Range, Target Reflectivity <math>\rho \geq 60\%</math> <sup>2)</sup></b>	250 m
<b>Max. Range, Target Reflectivity <math>\rho \geq 20\%</math> <sup>2)</sup></b>	150 m
<b>Max. Number of Targets per Pulse <sup>3)</sup></b>	5
<b>Minimum Range</b>	2 m
<b>Accuracy <sup>4) 6)</sup> / Precision <sup>5) 6)</sup></b>	15 mm / 10 mm
<b>Field of View (selectable)</b>	360°
<b>Scan Speed (selectable)</b>	up to 200 scans/sec

- 1) Rounded values.
- 2) Typical values for average conditions. Maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence, and for atmospheric visibility of 23 km. In bright sunlight, the max. range is shorter than under overcast sky.
- 3) If more than one target is hit, the total laser transmitter power is split and, accordingly, the achievable range is reduced.
- 4) Accuracy is the degree of conformity of a measured quantity to its actual (true) value.
- 5) Precision, also called reproducibility or repeatability, is the degree to which further measurements show the same result.
- 6) One sigma @ 50 m range under RIEGL test conditions.

### IMU/GNSS Performance <sup>7)</sup>

	IMU (Option A)	IMU (Option B)
<b>Position Accuracy</b>	typ. 20 - 50 mm	typ. 20 - 50 mm
<b>Roll &amp; Pitch Accuracy</b>	0.015°	0.005°
<b>Heading Accuracy</b>	0.05° / 0.025° <sup>8)</sup>	0.015°

- 7) One sigma values, no GNSS outage, with DMI option, post-processed using base station data.
- 8) Improved heading accuracy with dual antenna option @ 2 m base line.

### Electrical Data

<b>Power Supply Input Voltage</b>	11 - 15 V DC
<b>Power Consumption</b>	typ. 77 W (max. 228 W) <sup>9)</sup>

9) with 2 x 12 MP RIEGL camera

### Interfaces

Interfaces Measuring Head (VMY-2MH)	VM Power Supply Box	Interface Unit (VM-IU)
4 x trigger pulse, exposure pulse, NMEA data (e.g. for optional cameras or additional devices) 1 x PPS out pulse for synchronization of additional device 1 x secondary antenna connector for GPS azimuth measurement subsystem	1x DMI input (for distance measuring indicator; odometer) 3x power supply socket (2x 24V / 1x 12V)	4x LAN 1 Gbit/sec M12 sockets, 3 ports pre-configured 4x LAN 1 Gbit/sec RJ45 sockets, 2 ports pre-configured 4x USB 3.0 (e.g. image data transfer from FLIR Ladybug®5+) 1x display port 1x WLAN (integrated antenna) 1x Bluetooth (integrated antenna) 2x slot for removable hard disk 1x power supply input (+24V DC) 1x power supply output (+24V DC) for display (touch screen)



at a glance

**RIEGL VMY®-2**



Watch our videos!  
[youtube.com/rieglidar](https://youtube.com/rieglidar)

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