

# ▲ PEAKTRONICS

The Peaktronics AMI-103 AC Motor Interface is used to interface common electrical control signals to AC actuators. The unit provides the motor drive circuits, protection circuits, and isolation between the control inputs and motor outputs. A wide range of external control signals can be used to Open and Close the actuator. The unit accepts commonly used 120VAC signals from PLC modules, relay circuits, triac outputs, or solid state relay circuits. Alternatively, signals from a number of electronic sources, including TTL, CMOS, analog drivers, open collector outputs, and low voltage AC outputs, can be used.

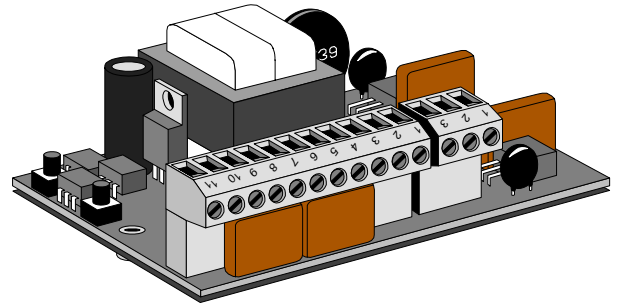
The unit has a built-in repeat cycle timer that can be independently enabled or disabled for Open and Close. The timer can be adjusted for 0.1 to 2 seconds "ON" time and for 0.5 to 10 seconds "OFF" time. Since some AC motors cannot be switched instantly from open to close operation, the unit provides an adjustable input delay feature.

The unit can be configured for 2-wire or 3-wire control. In 2-wire control, the control signal is applied to the Open input to drive the actuator *open*. When the control signal is removed, or driven to 0V, the actuator will automatically close. In 3-wire control, both control signals (Open and Close) are used to drive the actuator toward *open* or *closed* as desired. When both signals are removed, or driven to 0V, the actuator remains at its last position.

The unit also features a red LED indicator (for the *open* output), a green LED indicator (for the *closed* output), an on-board fuse, two removable screw terminal strips (for easy servicing), and on-board switches to manually open or close the actuator. An auxiliary +24VDC power output (that is isolated from the motor and control signals) can be used to power a 4-20mA or 0-5 / 10V

## AMI-103

### AC Motor Interface



AMI-103  
AMI-103A  
AMI-103B

transmitter. A transmitter (such as the Peaktronics XMA-105 or XMA-106) can be used to provide a position feedback signal from a feedback potentiometer (such as the Peaktronics POT-102).

The unit comes with standoff mounts and includes an insulating sheet that allows the unit to be mounted directly to the actuator housing or bracket. The unit is rated for 5A at 60°C when properly mounted to a metal bracket or metal actuator housing. The AMI-103 is rated for 117VAC  $\pm 10\%$ , the AMI-103A is rated for 234VAC  $\pm 10\%$ , and the AMI-103B is rated for 24VAC  $\pm 10\%$ .

## FEATURES

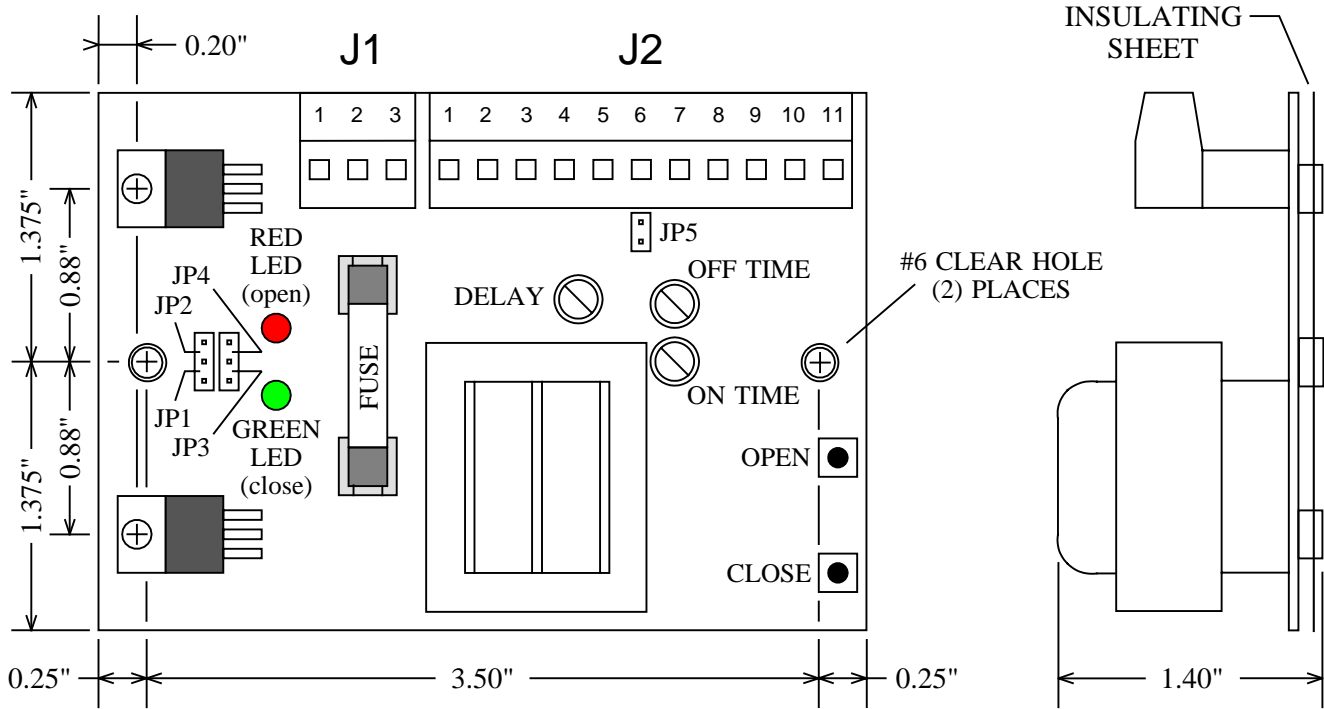
- On/Off Controller for 24VAC, 117VAC, or 234VAC actuators.
- Accepts wide range of AC or DC control signals.
- Accepts open collector control signal for easy interface to common bus modules.
- On-board switches for manual control.
- Configurable for 2-wire control (Open input only) or 3wire control (Open/Close inputs).
- On-board +24VDC output to power feedback transmitter and/or open collector inputs.
- Built-in repeat cycle timer for *open*, *close*, or both.
- Control inputs, motor outputs, and +24VDC output are electrically isolated from one another.

# OUTLINE

117VAC AMI-103

234VAC AMI-103A

24VAC AMI-103B

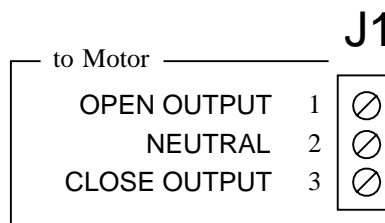


## ELECTRICAL CONNECTIONS

OPEN TIMER	JUMPER PLUG
ENABLED	JP1
DISABLED	JP2

CLOSE TIMER	JUMPER PLUG
ENABLED	JP3
DISABLED	JP4

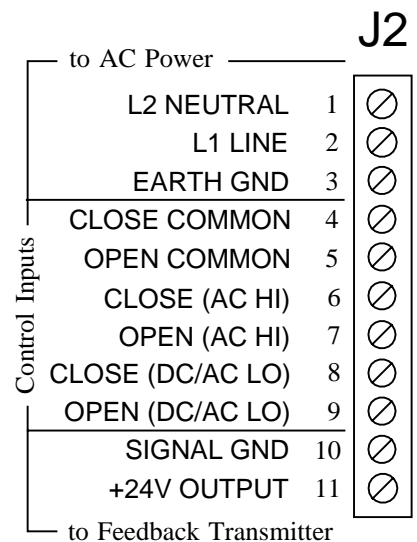
NOTE: The open output will be disabled if neither JP1 or JP2 is installed. Likewise, the close output is disabled if neither JP3 or JP4 is installed.



### JP5 JUMPER PLUG

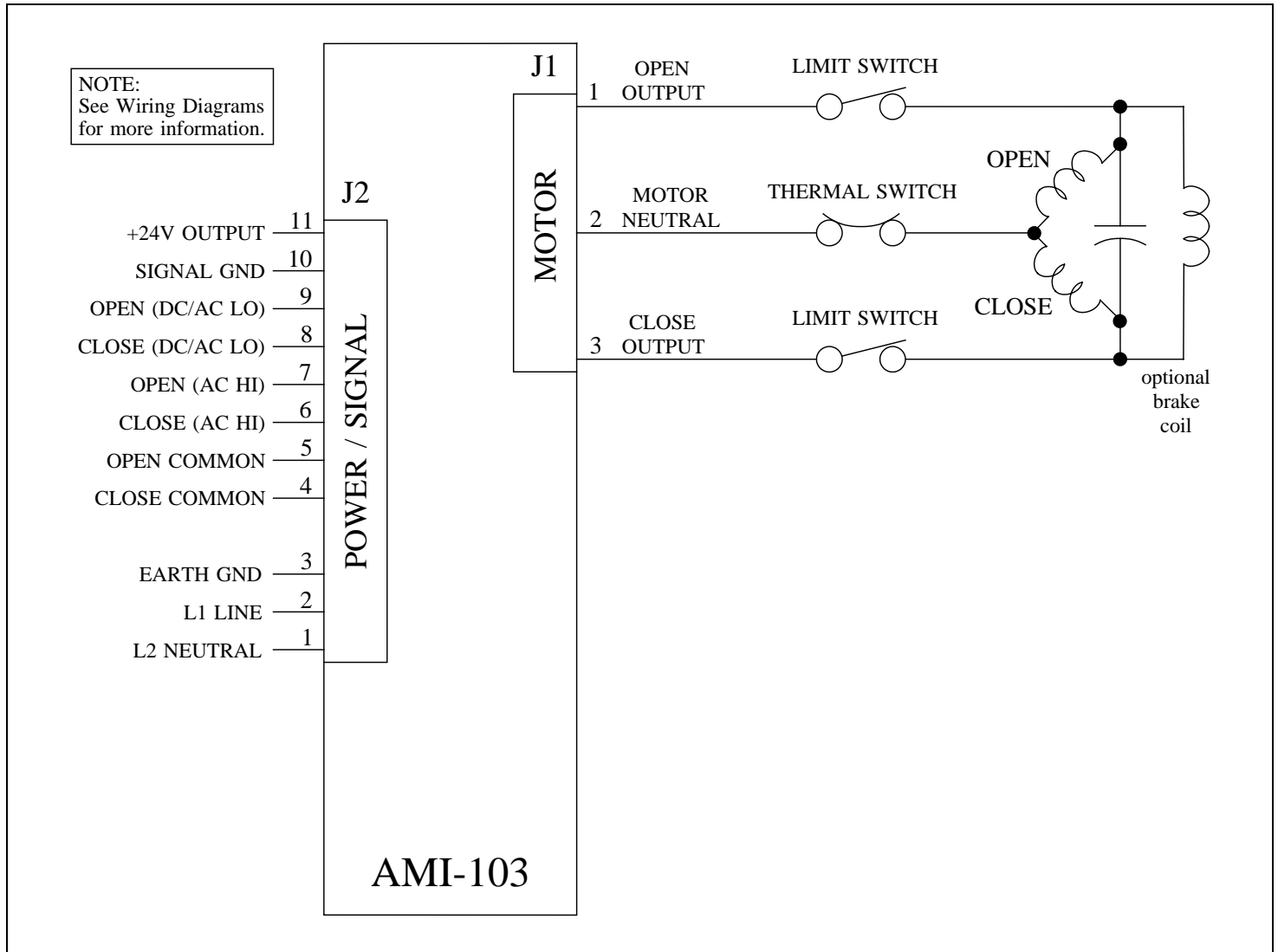
INSTALL for 3-wire control (Open and Close inputs)

REMOVE for 2-wire control (Open input only)



NOTE: Control Input connections are isolated from the Feedback Transmitter connections.

## BLOCK DIAGRAM



## DESCRIPTION

The AMI-103 comes in three versions to accommodate different voltage applications. The AMI-103 is rated for 117VAC  $\pm 10\%$ ; the AMI-103A is rated for 234VAC  $\pm 10\%$ , and the AMI-103B is rated for 24VAC  $\pm 10\%$ . The units come with standoff mounts for direct mounting to a bracket (insulating sheet is included).

The AMI-103 units are rated for 5A motors when properly mounted to a suitable metal plate or bracket. To provide sufficient heatsinking, these units **require** screw mounting through all four standoffs.

**CAUTION !** These units are intended to be mounted in an appropriate enclosure to avoid electrical shocks. High voltages are present on the outside of the unit when power is applied. AC power should be disconnected prior to any wiring of these units. A heater and thermostat should be used where condensation may occur.

## POWER / SIGNAL (J2)

Power is connected to pins 1, 2, and 3 as shown in the Block Diagram. The fuse installed on the unit is rated for maximum output current that can be safely delivered by the AC outputs. To prevent damage to the unit, replacement fuses must not exceed a rating of 6.3A. Smaller fuse sizes can be used with smaller motors - consult the actuator manufacturer for appropriate fuse size and type.

The control signal to open the actuator is connected to either pin 7 or pin 9 (**do not** connect both inputs at the same time) using pin 5 (OPEN COMMON) as the return. The close control signal is connected to either pin 6 or pin 8 (**do not** connect both at the same time) using pin 4 (CLOSE COMMON) as the return. The AC HI inputs (pins 6 and 7) are suitable for 120VAC control signals, while the DC/AC LO inputs are used for either DC electronic signals (such as TTL, CMOS, etc.) or AC control signals up to 90VAC. Open collector control signals can also be used - see Wiring Diagrams for details.

Pin 11 of J2 provides an auxiliary +24VDC output which can be used to power an output transmitter. SIGNAL GND (pin 10) is used as the return line for the transmitter. SIGNAL GND (pin 10), OPEN COMMON (pin 5), and CLOSE COMMON (pin 4) are isolated from the motor outputs on J1 as well as from each other. Pin 4 and 5 **should not** be connected to pin 10 when using control signals that are not isolated from the AC power line (pins 1, 2, and 3).

## MOTOR (J1)

Pin 1 should be connected to the motor winding that moves the actuator toward the *open* position, and conversely, pin 3 is connected to the winding that moves the actuator toward the *closed* position. Pin 2 is the neutral or common wire to the motor windings. The AMI-103 is suitable for powering most dynamic brakes used with electric actuators; however, consult the actuator manufacturer for more information.

## OUTPUT INDICATORS

The AMI-103 units have on-board indicators that identify when one of the motor outputs is turned on. When the open output is turned on, the red LED indicator will turn on, and when the close output is turned on the green LED indicator will turn on (see Outline).

Many actuators are equipped with limit switches at the *open* and *closed* positions which are intended to disconnect power to the motor to prevent mechanical dam-

age. For this reason, it is possible that the AMI-103 will indicate that one of the motor outputs is turned on when the actuator is not in motion. However, it should be noted that when the indicator is on, power is applied to the motor output.

## INPUT DELAY

Since some AC motors do not operate correctly when power is instantaneously switched between the Open and Close windings, the AMI-103 provides an input delay. If one output is on and the control signal inputs are switched to reverse the motor, the unit will delay turning on the other output. This delay is adjustable; see Specifications under "Control Adjustments" for delay period and Outline for location of the adjustment. When both outputs are off and a control input signal is applied, the Input Delay setting causes a delay in turning on the associated output. If the control signal is removed before the end of the delay period, the associated output will not turn on.

## OPEN and CLOSE SWITCHES

The AMI-103 provides on-board switches that allow manual operation from the unit - see Outline for location of the switches. Pressing the *open* switch will turn on the Open output (J1 pin 1), while pressing the *close* switch turns on the Close output (J1 pin 3). Since the OPEN and CLOSE switches replace the control signal inputs, the Input Delay function effects the switch operation in the same manner as a control signal - refer to INPUT DELAY for more details.

To protect against turning on both outputs at the same time, the AMI-103 will not turn on one of the outputs until the other output has turned off. Additionally, if both control signals are applied at the same time, the unit will turn off both outputs. This is true of any combination of control signals or on-board switch operation. For example, if a PLC is applying a control signal to the CLOSE input while someone is pressing the *open* switch, both outputs will be turned off.

## 2-WIRE / 3-WIRE CONTROL (JP5)

JP5 is used to configure the unit for either 2-wire or 3-wire control - see Outline for location and setting of JP5. In 3-wire control, the Open input signal is used to turn on the Open output (J1 pin 1), and the Close input signal is used to turn on the Close output (J1 pin 3).

In 2-wire control, only the Open input signal is used, and the Close input terminals (J2 pins 4, 6, and 8) must not be connected. The Close output will always be turned on until the Open input signal is applied, at which time the Close output is turned off and the Open output will turn on. When the Open input signal is applied, the manual Open switch will have no effect, while the manual Close switch will turn off both outputs. When the Open input signal is not applied, the manual Close switch will have no effect, while the manual Open switch will turn off the Close output and turn on the Open output.

## REPEAT CYCLE TIMER

The AMI-103 has a built-in repeat cycle timer that can be used to adjust the actuator speed. The timer automatically cycles the output on and off whenever the associated control input is applied. The ON time is adjustable from 0.1 to 2 seconds, while the OFF time is adjustable from 0.5 to 10 seconds. The timer function can be enabled or disabled for each output independently by installing jumpers for the desired operation. See Outline for location of adjustments and jumpers.

## SPECIFICATIONS

### POWER REQUIREMENTS

AMI-103: 117VAC  $\pm 10\%$ , 50/60 Hz  
 AMI-103A: 234VAC  $\pm 10\%$ , 50/60 Hz  
 AMI-103B: 24VAC  $\pm 10\%$ , 50/60 Hz  
 3.6 VA typical (not including output load)  
 Fuse Type: 6.3A 3AG Time Delay

### AC HI CONTROL SIGNAL INPUTS

Maximum Input Voltage:  
 130VAC 50/60 Hz (20 mA typical @ 60 Hz)  
 Minimum ON Voltage:  
 85VAC 50/60 Hz (13 mA typical @ 60 Hz)  
 Maximum OFF Voltage:  
 60VAC 50/60 Hz (8.8 mA typical @ 60 Hz)  
 Maximum OFF State Input Current:  
 7.5 mA @ 60 Hz / 6 mA @ 50 Hz

### DC/AC LO CONTROL SIGNAL INPUTS

Maximum Input Voltage:  
 130VDC (4 mA typical)  
 90VAC 50/60 Hz (3.3 mA typical)  
 Minimum ON Voltage:  
 2.4VDC (0.4 mA maximum), TTL compatible  
 1.9VAC (0.16 mA typical)  
 Maximum OFF Voltage:  
 1.8VDC  
 1.3VAC  
 Maximum OFF State Input Current:  
 0.25 mA DC / 0.1 mA AC

### +24V OUTPUT

24VDC  $\pm 5\%$  @ 45mA max

### AC MOTOR OUTPUTS

Off-state Leakage Current: <15mA  
 Maximum Load Current @ 60°C:  
 5A (when properly mounted)

### CONTROL ADJUSTMENTS

Cycle Timer, ON Time: 0.1 to 2 seconds  
 Cycle Timer, OFF Time: 0.5 to 10 seconds  
 Input Delay:  
 0.056 to 1.5 second, switching inputs (3-wire)  
 0.017 to 1 second, single input (3-wire)  
 0.04 to 1.5 second (2-wire)

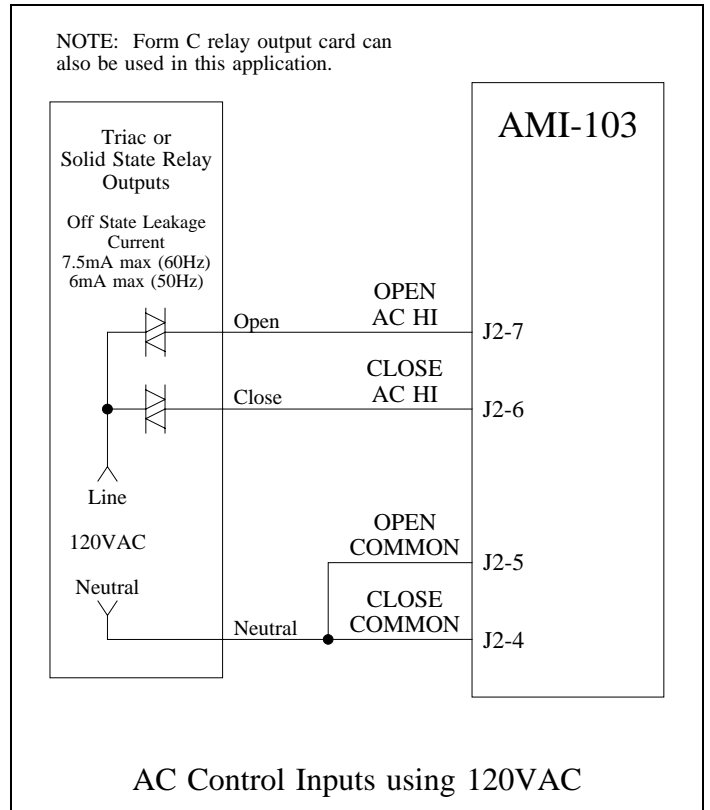
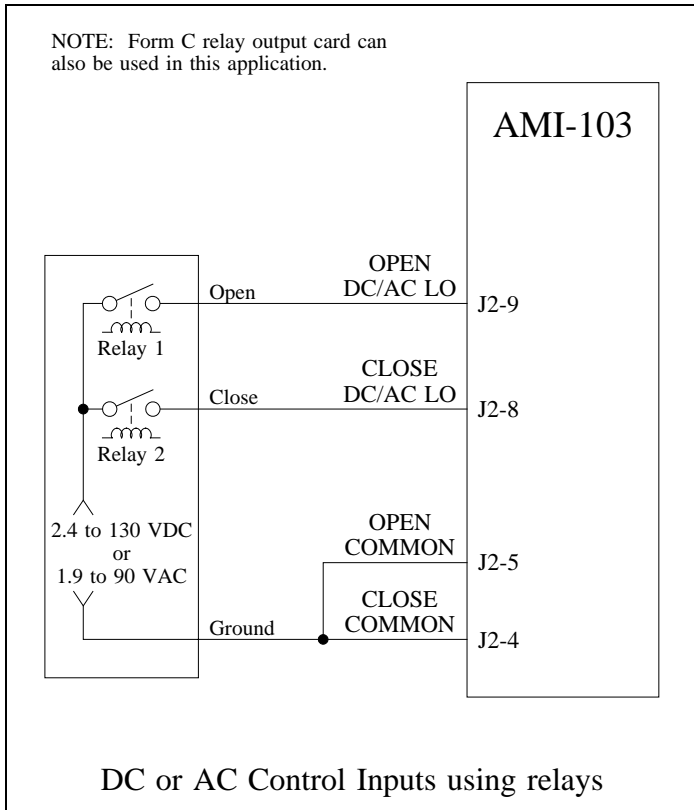
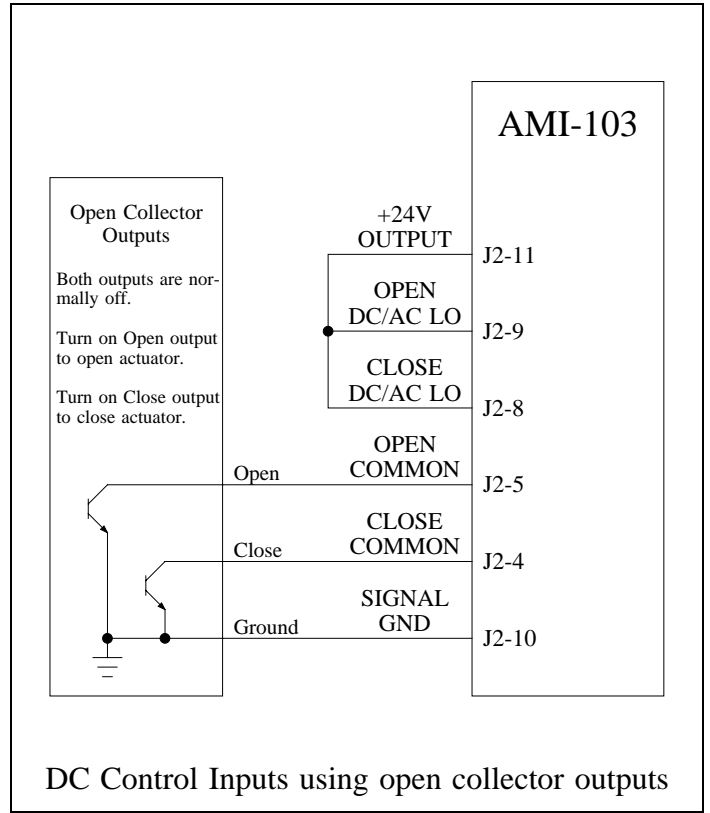
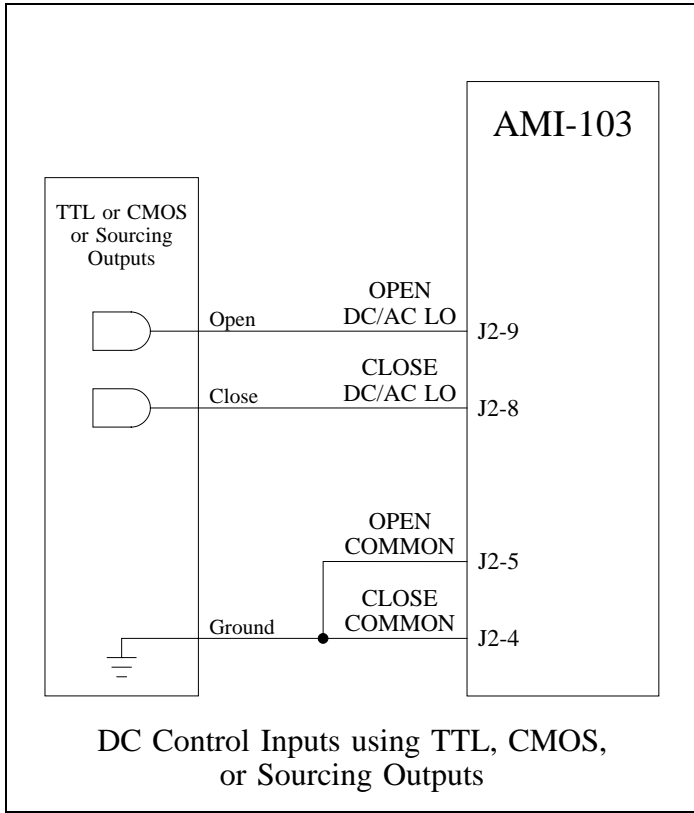
### ENVIRONMENTAL

Operating Temperature Range: 0 °C to 60 °C  
 Storage Temperature Range: -40 °C to 85 °C  
 Relative Humidity Range: 0 to 90 % (noncondensing)

## WIRING DIAGRAMS

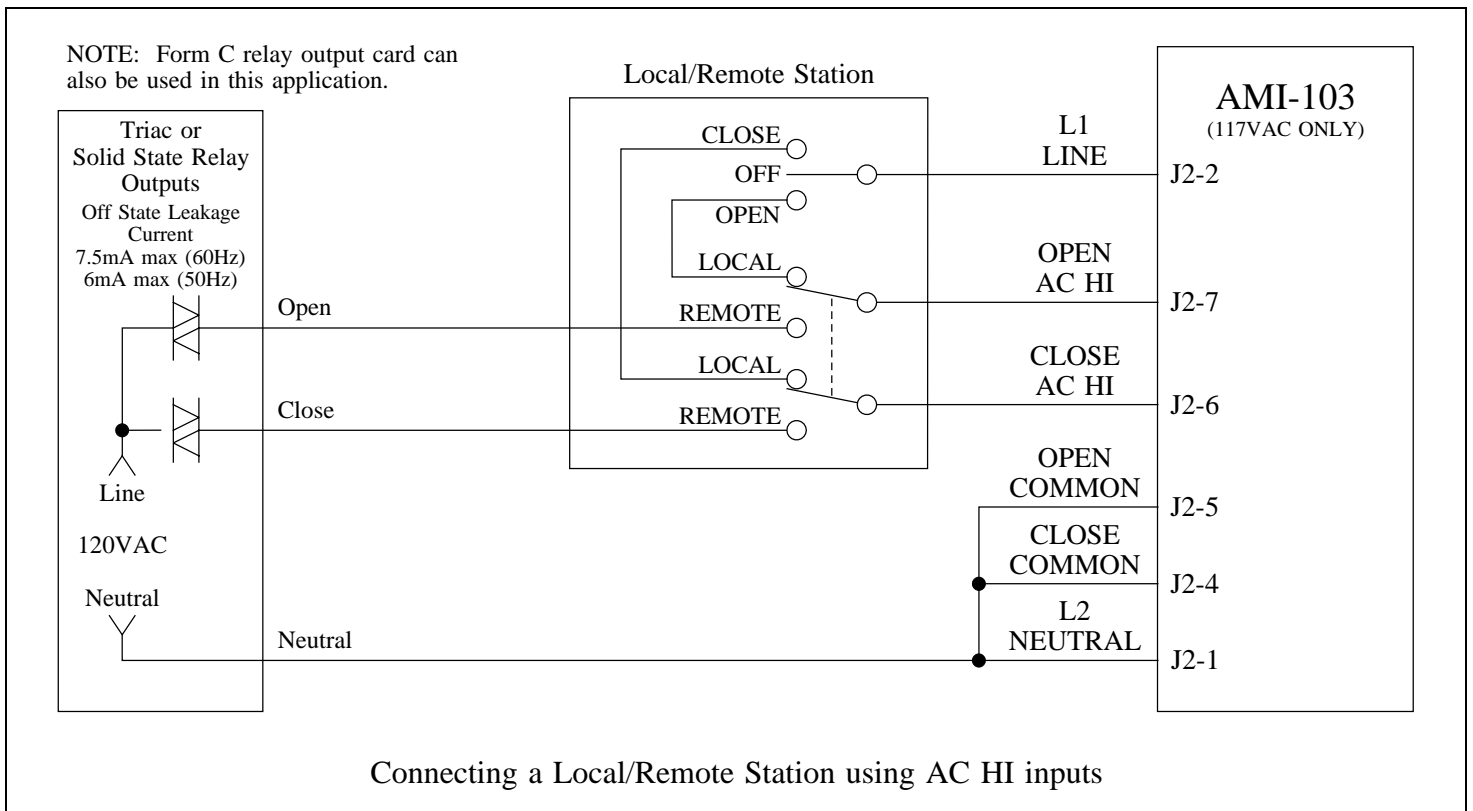
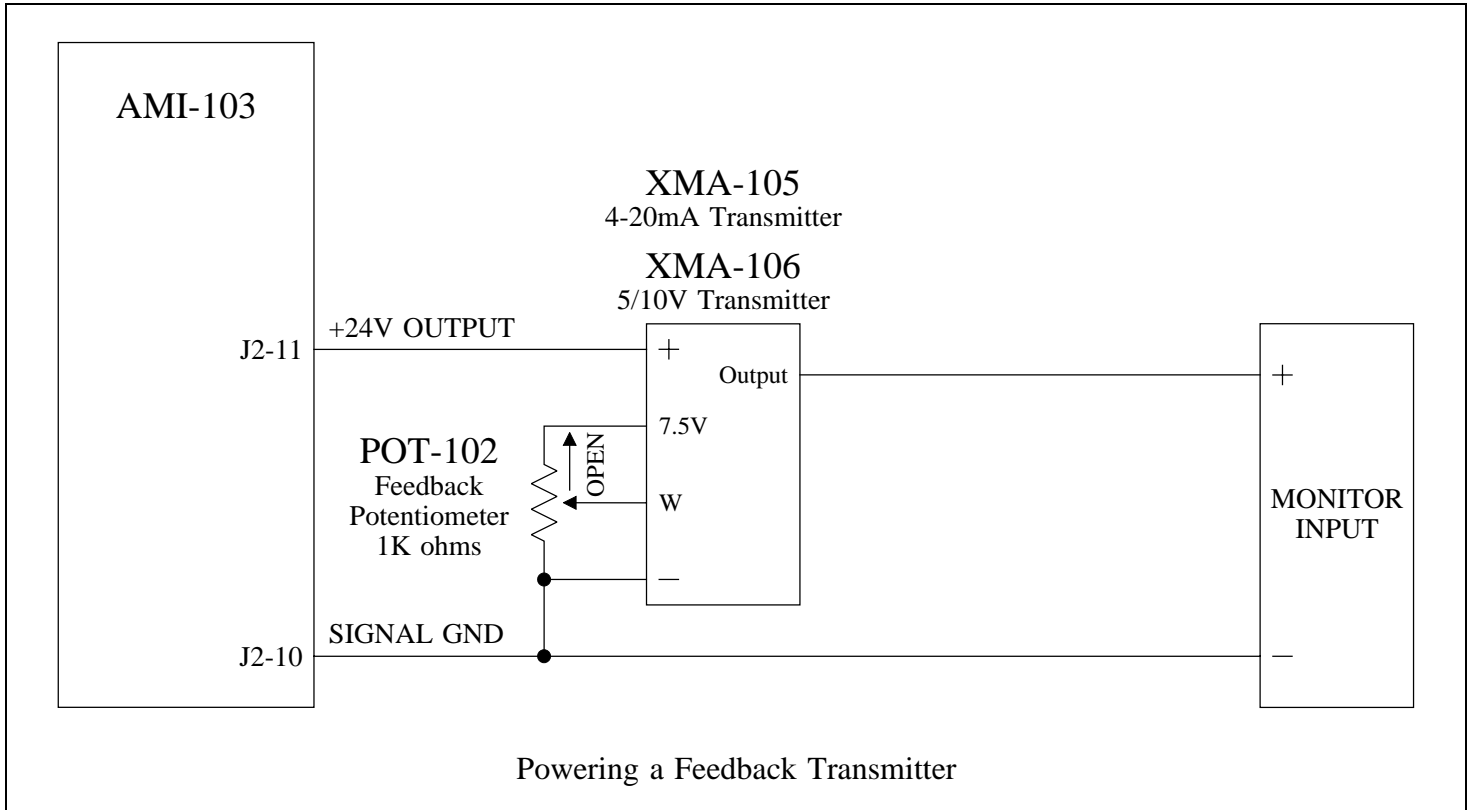
### Input Signal Configurations

(connect OPEN input only for 2-Wire Control)



## WIRING DIAGRAMS

### Special Applications



## WIRING DIAGRAMS

### Special Applications

